

Model Answer (AS-633)

Pre Ph.D. Course Work Examination, 2013-14
Mathematics

Geometry of Finsler spaces

I. (i). Let $F(x^i, y^i)$ be a function of line element (x^i, y^i) which satisfies

- $F(x^i, y^i)$ is positively homogeneous of degree one in y^i .
- $F(x^i, y^i)$ is positive, if not all y^i vanish simultaneously.
- The quadratic form $\partial_i \partial_j F^2 \cdot \xi^i \xi^j$ is positive for all variables ξ^i .

Let $P(x^i)$ and $Q(x^i + dx^i)$ be two neighbouring point in R.

- The distance ds between P and Q, is given by
- $$ds = F(x^i, dx^i).$$

The space equipped with such metric is called a Finsler space.

(ii) Metric tensor g_{ij} is defined by

$$\begin{aligned} g_{ij} &= \frac{1}{2} \partial_i \partial_j F^2 \\ &= \frac{1}{2} \partial_j \partial_i F^2 \\ &= g_{ji}. \end{aligned}$$

$$\begin{aligned} \text{(iii). } c_{ijk} y^i &= \frac{1}{2} \partial_k g_{ij} \cdot y^i \\ &= \frac{1}{4} \partial_k \partial_i \partial_j F^2 \cdot y^i \\ &= \partial_i \left(\frac{1}{2} g_{jk} \right) y^i \\ &= 0 \quad \text{by Euler's theorem.} \end{aligned}$$

$$\begin{aligned} \text{(iv). } r_{jk}^i &= g^{ip} \cdot r_{pj} \\ &= g^{ip} \cdot \frac{1}{2} (\partial_j g_{pk} + \partial_k g_{jp} - \partial_p g_{jk}) \end{aligned}$$

Since the degree of hom. of g_{ij} is zero. Therefore the degree of hom. of r_{jk}^i is zero.

$$\begin{aligned} \text{(v). } y_i &= g_{ij} y^j \\ &= \frac{1}{2} \partial_i \partial_j F^2 \cdot y^j \\ &= \partial_j (\frac{1}{2} \partial_i F^2) \cdot y^j \\ &= \frac{1}{2} \partial_i F^2 \quad \text{by Euler's theorem.} \end{aligned}$$

$$\text{(vi). } \frac{\delta x^i}{\delta t} = \frac{dx^i}{dt} + p_{jk}^i x^j y^k.$$

$$\text{(vii). } G_{jk}^i = \partial_j \partial_k G^i$$

and $G^i = \frac{1}{2} r_{jk}^i y^j y^k$.

Since the degree of hom. of r_{jk}^i is zero, the degree of hom. of G^i is two. Hence the degree of hom. of G_{jk}^i is zero.

viii). A connection is called metrical if the covariant derivative of the metric tensor with respect to the connection vanishes identically.

ix). A Finsler space is called Affinely connected space if

$$G_{jkh}^i = 0.$$

$$\text{i.e. } \partial_h G_{jk}^i = 0$$

i.e. Berwald connection coeff. G_{jk}^i is independent of directional argument.

(x). Since $B_k g_{jh} = \gamma_r G^r_{jkh}$

and a Finsler space is called a Landsberg space if

$$\gamma_r G^r_{jkh} = 0. \text{ Hence } B_k g_{jh} = 0.$$

(xi). Ricci tensor $H_{jk} \stackrel{\text{def}}{=} H^s_{jks}$.

(xii). A Finsler space is called symmetric if

$$B_m H^i_{jkh} = 0.$$

(xiii). $\mathcal{L} y^i = v^r B_r y^i + (\partial_r y^i) y^s B_s v^r - y^r B_r v^i$
 $= v^r \cdot 0 + \delta^i_r y^s B_s v^r - y^r B_r v^i$
 $= 0.$

(xiv). An infinitesimal transformation is said to be a conformal transformation if it preserves angle

(xv). Projective deviation tensor w_k^i is defined by

$$w_k^i = H_k^i - H \cdot S_k^i - \frac{1}{n+1} (\partial_r H^r_k - \partial_k H) \cdot y^i$$

(xvi). A Finsler space F^n ($n > 2$) is projectively flat iff it is a space of scalar curvature.

Q.

Q.2. Geodesic.

Geodesic is the path of extremum (stationary) distance between two points.

A curve $c: x^i = x^i(t)$ with end points P_0 and P_1 is a Geodesic, if the distance between P_0 and P_1 along c is stationary.

In a Finsler space, the distance betⁿ two points $x^i \& x^i + dx^i$ is given by

$$ds = F(x^i, dx^i)$$

$$= F(x^i, dt \cdot \frac{dx^i}{dt})$$

$$= \oint F(x^i, \dot{x}^i) dt$$

$$\frac{ds}{dt} = F(x^i, \dot{x}^i)$$

$$\therefore s = \int_{t_0}^{t_1} F(x^i, \dot{x}^i) dt \quad \text{along } c$$

Since c is a Geodesic, this integral is station

$$\therefore \frac{\partial F}{\partial x^i} - \frac{d}{dt} \frac{\partial F}{\partial \dot{x}^i} = 0$$

$$\begin{aligned} \text{Now } \frac{\partial F}{\partial x^k} &= \frac{\partial}{\partial x^k} \left[\{g_{ij}(x, \dot{x}) \dot{x}^i, \dot{x}^j\}^{1/2} \right] \\ &= \frac{1}{2 \{g_{ij}(x, \dot{x}) \dot{x}^i, \dot{x}^j\}^{1/2}} \left[(\partial_k g_{ij}) \dot{x}^i \dot{x}^j \right] * \end{aligned}$$

$$\frac{\partial F}{\partial \dot{x}^k} = \frac{1}{2 \{ g_{ij}(x, \dot{x}) \dot{x}^i \dot{x}^j \}^{1/2}} \left\{ (\partial_k g_{ij}) \dot{x}^i \dot{x}^j + g_{ij} \delta_k^i \dot{x}^j + g_{ij} \dot{x}^i \delta_k^j \right\}$$

$$= \frac{1}{2 \dot{s}} \left\{ 2 C_{ijk} \dot{x}^i \dot{x}^j + g_{jk} \dot{x}^j + g_{ik} \dot{x}^i \right\}.$$

$$= \frac{1}{2 \dot{s}} \left\{ 0 + g_{jk} \dot{x}^j + g_{ik} \dot{x}^i \right\}$$

$$= \frac{1}{\dot{s}} g_{jk} \dot{x}^j$$

$$\begin{aligned} \frac{d}{dt} \frac{\partial F}{\partial \dot{x}^k} &= -\frac{1}{\dot{s}^2} \ddot{s} g_{jk} \dot{x}^j + \frac{1}{\dot{s}} \left(\frac{\partial g_{jk}}{\partial x^n} \frac{\partial x^n}{\partial t} + \frac{\partial g_{jk}}{\partial x^n} \frac{\partial \dot{x}^n}{\partial t} \right) \dot{x}^j \\ &\quad + \frac{1}{\dot{s}} g_{jk} \frac{d}{dt} \dot{x}^j. \end{aligned}$$

$$\begin{aligned} &= -\frac{1}{\dot{s}^2} \ddot{s} g_{jk} \dot{x}^j + \frac{1}{\dot{s}} \left\{ (\partial_n g_{jk}) \dot{x}^n + (\dot{\partial}_n g_{jk}) \dot{x}^n \right\} \dot{x}^j \\ &\quad + \frac{1}{\dot{s}} g_{jk} \ddot{x}^j \end{aligned}$$

Therefore Euler eqⁿ becomes.

$$\frac{\partial F}{\partial x^i} - \frac{d}{dt} \frac{\partial F}{\partial \dot{x}^i} = 0$$

$$\begin{aligned} \frac{1}{2 \dot{s}} (\partial_k g_{ij}) \dot{x}^i \dot{x}^j + \frac{1}{\dot{s}^2} \ddot{s} g_{jk} \dot{x}^j - \frac{1}{\dot{s}} (\partial_n g_{jk} \dot{x}^n + \dot{\partial}_n g_{jk} \dot{x}^n) \dot{x}^j \\ - \frac{1}{\dot{s}} g_{jk} \ddot{x}^j = 0 \end{aligned}$$

$$\frac{1}{2} (\partial_k g_{ij}) \dot{x}^i \dot{x}^j + \frac{1}{\dot{s}} \ddot{s} g_{jk} \dot{x}^j - \partial_i g_{jk} \dot{x}^i \dot{x}^j - 2 C_{jkn} \dot{x}^n \dot{x}^j - g_{jk} \ddot{x}^j = 0$$

$$\begin{aligned} \frac{1}{2} (\partial_k g_{ij}) \dot{x}^i \dot{x}^j + \frac{1}{\dot{s}} \ddot{s} g_{jk} \dot{x}^j - \partial_i g_{jk} \dot{x}^i \dot{x}^j - 0 - g_{jk} \ddot{x}^j = 0 \\ \left\{ \text{as } C_{jkn} \dot{x}^j = 0 \right. \end{aligned}$$

$$\frac{1}{2} (\partial_R g_{ij} - 2\partial_i g_{jk}) \ddot{x}^i \dot{x}^j - g_{jk} \ddot{x}^i + \frac{1}{s} \ddot{s} g_{jk} \dot{x}^i = 0$$

$$\frac{1}{2} (\partial_i g_{jk} \ddot{x}^i \dot{x}^j + \partial_j g_{ik} \ddot{x}^i \dot{x}^j - \partial_k g_{ij} \ddot{x}^i \dot{x}^j) + g_{jk} \ddot{x}^j - \frac{1}{s} \ddot{s} g_{jk} \dot{x}^j = 0$$

$$\frac{1}{2} (\partial_i g_{jk} \ddot{x}^i \dot{x}^j + \partial_j g_{ik} \ddot{x}^i \dot{x}^j - \partial_k g_{ij} \ddot{x}^i \dot{x}^j) + g_{jk} \ddot{x}^j - \frac{1}{s} \ddot{s} g_{jk} \dot{x}^j = 0$$

interchanging $i \leftrightarrow j$ in second term in Bracket.

$$r_{ijk} \ddot{x}^i \dot{x}^j + g_{jk} \ddot{x}^j - \frac{\ddot{s}}{s} g_{jk} \dot{x}^j = 0$$

Multiply by g^{kh} and taking summation over k .

$$r_{ij}^h \ddot{x}^i \dot{x}^j + g_j^h \ddot{x}^j - \frac{\ddot{s}}{s} g_j^h \dot{x}^j = 0$$

$$\therefore \boxed{\ddot{x}^h + r_{ij}^h \ddot{x}^i \dot{x}^j - \frac{\ddot{s}}{s} \dot{x}^h = 0}$$

differential eqn of Geodesic.

If we take arc length as parameter

$$\text{then } \dot{x}^i = x'^i \dot{s}$$

$$\ddot{x}^i = x''^i \dot{s}^2 + x'^i \ddot{s}$$

$$\text{and use } r_{ij}^h(x^i, \dot{x}^i) = r_{ij}^h(x^i, x'^i)$$

then eqn will become

$$\boxed{x''^i + r_{jk}^i x'^j x'^k = 0}$$

3. Ricci Commutation Formula for Berwald covariant differentiation.

$$B_j B_k X^i - B_k B_j X^i = X^\gamma H_{\gamma k j}^i - \partial_\gamma X^i \cdot H_{j k \gamma}^\infty$$

where $H_{\gamma k j}^i$ Berwald curvature tensor
 $H_{\gamma k j}^i = \{ \partial_j G_{\gamma k}^i - G_{s k \gamma}^i G_{s j}^i + G_{s j}^i G_{s k}^i - \gamma / k \}$

Berwald torsion tensor
and $H_{j k \gamma}^\infty = \{ \partial_j G_{k \gamma}^\infty + G_{s k \gamma}^\infty G_{s j}^\infty - \gamma / k \}$

Proof.

$$B_j (B_k X^i) = \partial_j (B_k X^i) - (\partial_\gamma B_k X^i) G_{\gamma j}^i + B_k X^\gamma \cdot G_{\gamma j}^i - B_\gamma X^i \cdot G_{j k}^\infty$$

$$\begin{aligned} B_j B_k X^i &= \partial_j \left\{ \underbrace{\partial_k X^i}_{1} - (\partial_\gamma X^i) G_{\gamma k}^\infty + X^\gamma G_{\gamma k}^i \right\} \\ &\quad - \partial_\gamma \left\{ \underbrace{\partial_k X^i}_{2} - (\partial_s X^i) G_{s k}^s + X^s G_{s k}^i \right\} G_{\gamma j}^\infty \\ &\quad + \left\{ \underbrace{\partial_k X^\gamma}_{3} - (\partial_s X^\gamma) G_{s k}^s + X^s G_{s k}^\gamma \right\} G_{\gamma j}^i \\ &\quad - \left\{ \underbrace{\partial_\gamma X^i}_{2} - (\underbrace{\partial_s X^i}_{3}) G_{s \gamma}^s + X^s G_{s \gamma}^i \right\} G_{j k}^\infty \end{aligned}$$

$$\begin{aligned} B_k B_j X^i &= \partial_k \left\{ \underbrace{\partial_j X^i}_{1} - (\partial_\gamma X^i) G_{\gamma j}^\infty + X^\gamma G_{\gamma j}^i \right\} \\ &\quad - \partial_\gamma \left\{ \underbrace{\partial_j X^i}_{2} - (\partial_s X^i) G_{s j}^s + X^s G_{s j}^i \right\} G_{k \gamma}^\infty \\ &\quad + \left\{ \underbrace{\partial_j X^\gamma}_{3} - (\partial_s X^\gamma) G_{s j}^s + X^s G_{s j}^\gamma \right\} G_{k \gamma}^i \\ &\quad - \left\{ \underbrace{\partial_\gamma X^i}_{2} - (\underbrace{\partial_s X^i}_{3}) G_{s \gamma}^s + X^s G_{s \gamma}^i \right\} G_{k j}^\infty \end{aligned}$$

After some calculation we get the result.

Above result can also be written as

$$X_{(j)(k)}^i - X_{(k)(j)}^i = X^\gamma H_{\gamma k j}^i - (\partial_\gamma X^i) H_{j k \gamma}^\infty$$

4. Recurrent Finsler Space.

A Finsler space F_n is said to be recurrent if its curvature tensor satisfies

$$B_m H_{Jkh}^i = \lambda_m \cdot H_{Jkh}^i \quad ; \quad H_{Jkh}^i \neq 0$$

where λ_m is a non-zero covariant vector called recurrence vector.

Theorem: The recurrence vector λ_m is indep. of the directional argument.

Proof: The recurrence vector λ_m is given by

$$B_m H_{Jkh}^i = \lambda_m H_{Jkh}^i$$

Contracting $i \neq h$, we get

$$B_m H_{Jk}^i = \lambda_m H_{Jk}^i$$

Since γ^j is Berwald covariant const. so transvecting above eqn by γ^j , we get

$$B_m H_k = \lambda_m H_k$$

Diff partially w.r.t. γ^j , we get

$$\partial_j B_m H_k = \partial_j \lambda_m \cdot H_k + \lambda_m \cdot \partial_j H_k$$

using comm. formula

$$B_m \partial_j H_k - H_k G_{Jmk}^\gamma = \partial_j \lambda_m \cdot H_k + \lambda_m \cdot \partial_j H_k$$

$$\therefore B_m H_{Jk} - H_k G_{Jmk}^\gamma = \partial_j \lambda_m \cdot H_k + \lambda_m \cdot \partial_j H_k$$

$$\text{Since } B_m H_{JK} = \lambda_m H_{JK}$$

so we get from above eq

$$-H_K G_{JmK}^{\gamma} = \dot{\gamma}_J \lambda_m \cdot H_K$$

Treating by y^k and using $G_{JmK}^{\gamma} y^k = 0$, we get

$$0 = \dot{\gamma}_J \lambda_m \cdot y^k H_K$$

$$\text{i.e. } 0 = \dot{\gamma}_J \lambda_m \cdot (n-1)H \quad \text{as } y^k H_K = (n-1)H$$

Since $n \neq 1$ & $H \neq 0$

$$\text{So } \dot{\gamma}_J \lambda_m = 0$$

5. Lie derivative of connection coeff. G_{JK}^i

$$\bar{x}^i = x^i + \epsilon v^i(x^k) \quad \dots (1)$$

$$\dot{\bar{x}}^i = \dot{x}^i + \epsilon \partial_h v^i \cdot \dot{x}^h \quad \dots (2)$$

Treating the trans. as a general shift.

$$\bar{G}_{JK}^i = G_{JK}^i(\bar{x}^h, \dot{\bar{x}}^h)$$

$$= G_{JK}^i(x^n + \epsilon v^n, \dot{x}^h + \epsilon \partial_h v^n \cdot y^r)$$

$$= G_{JK}^i(x^n, \dot{x}^h) + \epsilon v^n \partial_h G_{JK}^i + \epsilon \partial_h v^n \cdot y^r \dot{\partial}_h G_{JK}^i$$

$$d^v G_{JK}^i = \bar{G}_{JK}^i - G_{JK}^i$$

$$= \epsilon v^n \partial_h G_{JK}^i + \epsilon \partial_h v^n \cdot y^r \dot{\partial}_h G_{JK}^i \quad \dots (3)$$

Treating the trans(1) as a co-ordinate trans.

$$\bar{G}_{JK}^i = \frac{\partial \bar{x}^i}{\partial x^l} \frac{\partial x^m}{\partial \bar{x}^l} \frac{\partial x^n}{\partial \bar{x}^k} G_{mn}^l + \frac{\partial \bar{x}^i}{\partial x^l} \frac{\partial x^l}{\partial \bar{x}^j} \frac{\partial x^k}{\partial \bar{x}^k} G_{jk}^i$$

$$\text{From (1)} \quad \frac{\partial \bar{x}^i}{\partial x^l} = \frac{\partial x^i}{\partial x^l} + \epsilon \frac{\partial v^i}{\partial x^l} = s_J^i + \epsilon \partial_J v^i$$

$$\frac{\partial x^m}{\partial \bar{x}^l} = \frac{\partial x^m}{\partial x^l} - \epsilon \partial_h v^m \frac{\partial x^h}{\partial \bar{x}^l}$$

$$= \frac{\partial x^m}{\partial x^l} - \epsilon \partial_h v^m \left(\frac{\partial x^h}{\partial \bar{x}^l} - \epsilon \partial_h v^h \frac{\partial x^h}{\partial \bar{x}^l} \right)$$

$$= \delta_j^m - \epsilon \partial_h v^m (\delta_j^h - \epsilon \partial_j v^h \frac{\partial x^h}{\partial x^j})$$

$$\frac{\partial x^m}{\partial x^j} = \delta_j^m - \epsilon \partial_j v^m + \dots$$

$$\frac{\partial^2 m}{\partial x^j \partial x^k} = \frac{\partial}{\partial x^k} (\delta_j^m - \epsilon \partial_j v^m + \dots)$$

$$= 0 - \epsilon \partial_j \partial_j v^m \frac{\partial x^k}{\partial x^k} + \dots$$

$$= - \epsilon \partial_j \partial_j v^m (\delta_k^m - \epsilon \partial_k v^m + \dots) + \dots$$

$$= - \epsilon \partial_k \partial_j v^m + \dots$$

So

$$\bar{G}_{jk}^i = (\delta_j^i + \epsilon \partial_j v^i)(\delta_j^m - \epsilon \partial_j v^m + \dots)(\delta_k^n - \epsilon \partial_k v^n + \dots) G_{mn}^j$$

$$+ (\delta_j^i + \epsilon \partial_j v^i)(-\epsilon \partial_k \partial_j v^k + \dots)$$

$$= G_{jk}^i + G_{jk}^j \epsilon \partial_j v^i - \epsilon \partial_j v^m G_{mk}^i - \epsilon \partial_k v^n G_{jn}^i - \epsilon \partial_k \partial_j v^i + \dots$$

$$\therefore d^m G_{jk}^i = \epsilon \partial_j v^i G_{jk}^j - \epsilon \partial_j v^m G_{mk}^i - \epsilon \partial_k v^n G_{jn}^i - \epsilon \partial_k \partial_j v^i + \dots$$
--- (4)

Hence

$$\begin{aligned} f G_{jk}^i &= \lim_{\epsilon \rightarrow 0} \frac{d^u G_{jk}^i - d^m G_{jk}^i}{\epsilon} \\ &= \lim_{\epsilon \rightarrow 0} \frac{(\epsilon v^n \partial_n G_{jk}^i + \epsilon \partial_j v^h y^r \partial_h G_{jk}^i + \dots)}{-(\epsilon \partial_j v^i G_{jk}^j - \epsilon \partial_j v^m G_{mk}^i - \epsilon \partial_k v^n G_{jn}^i - \epsilon \partial_k \partial_j v^i + \dots)} \end{aligned}$$

$$\begin{aligned} f G_{jk}^i &= v^n \partial_n G_{jk}^i + \partial_j v^n y^r \partial_h G_{jk}^i - \partial_j v^i G_{jk}^j + \partial_j v^m G_{mk}^i \\ &\quad + \partial_k v^n G_{jn}^i + \partial_k \partial_j v^i \end{aligned}$$

Since

$$B_R B_J v^i = \partial_R (B_J v^i) - \partial_R B_J v^i: G_{RK}^r + B_J v^r G_{RK}^i - B_R v^i G_{JK}^r$$

$$B_R B_J v^i = \partial_R (\partial_J v^i + v^r G_{Jr}^i) - (B_J \cancel{\partial_R v^i} + v^s G_{rs}^i) G_{RK}^r$$

$$+ (\partial_J v^r + v^s G_{rs}^r) G_{RK}^i - (\partial_R v^i + v^s G_{rs}^i) G_{JK}^r$$

$$B_K B_J V^i = \partial_K \partial_J V^i + \partial_K V^r G_{rJ}^i + V^r \partial_K G_{rJ}^i - V^s G_{rs}^i G_{rk}^s \\ + \partial_J V^r G_{rk}^i + V^s G_{sj}^r G_{jk}^i - \partial_r V^i G_{jk}^r - V^s G_{sr}^i G_{jk}^r$$

$$\therefore \partial_K \partial_J V^i = B_K B_J V^i - \partial_K V^r G_{rJ}^i - V^r \partial_K G_{rJ}^i + V^s G_{rs}^i G_{rk}^r \\ - \partial_J V^r G_{rk}^i - V^s G_{sj}^r G_{jk}^i + \partial_r V^i G_{jk}^r + V^s G_{sr}^i G_{jk}^r$$

Hence

$$\begin{aligned} f G_{jk}^i &= V^h \partial_h G_{jk}^i + \partial_r V^r y^r \partial_h G_{jk}^i - \cancel{\partial_r V^i G_{jk}^i} + \cancel{\partial_r V^m G_{mk}^i} \\ &\quad + \cancel{\partial_k V^r G_{jn}^i} + (B_K B_J V^i - \cancel{\partial_K V^r G_{rJ}^i} - V^r \partial_K G_{rJ}^i + V^s G_{rs}^i G_{rk}^r \\ &\quad - \cancel{\partial_j V^r G_{jk}^i} + V^s G_{sj}^r G_{jk}^i + \cancel{\partial_r V^i G_{jk}^r} + V^s G_{sr}^i G_{jk}^r) \end{aligned}$$

$$f G_{jk}^i = B_K B_J V^i + \partial_r V^r y^r \partial_h G_{jk}^i + V^h \partial_h G_{jk}^i - V^r \partial_K G_{rJ}^i$$

$$+ V^s G_{js}^i G_{rk}^r - V^s G_{sj}^r G_{jk}^i + V^s G_{sr}^i G_{jk}^r$$

$$= B_K B_J V^i + (B_r V^h - V^s G_{sr}^h) y^r \partial_h G_{jk}^i + V^h \partial_h G_{jk}^i \\ - V^r \partial_K G_{rJ}^i + V^s G_{js}^i G_{rk}^r - V^s G_{sj}^r G_{jk}^i + V^s G_{sr}^i G_{jk}^r$$

$$= B_K B_J V^i + B_r V^h y^r \partial_h G_{jk}^i + V^r (\partial_r G_{jk}^i - \partial_K G_{rJ}^i) \\ + G_{js}^i G_{rk}^r - G_{hjk}^i G_{hr}^h + G_{sr}^i G_{jk}^r - G_{sk}^i G_{jk}^r \}$$

$$f G_{jk}^i = B_K B_J V^i + V^r H_{jk}^r + B_r V^h y^r G_{jk}^i$$

Since G_{jk}^i is symmetric in $j \& k$.

So $\boxed{f G_{jk}^i = B_J B_K V^i + H_{kj}^r V^r + B_r V^h y^r G_{jk}^i}$

$$6. \underline{\text{Proof}}. L G_{JK}^i = B_J B_K v^i + H_{KJ\gamma}^i v^\gamma + G_{JK\gamma}^i y^s B_S v^\gamma$$

$$\begin{aligned} B_h L G_{JK}^i &= B_h B_J B_K v^i + B_h H_{KJ\gamma}^i v^\gamma + H_{KJ\gamma}^i B_h v^\gamma \\ &\quad + B_h G_{JK\gamma}^i y^s B_S v^\gamma + G_{JK\gamma}^i y^s B_h B_S v^\gamma \end{aligned}$$

interchanging $h \leftrightarrow j$, we have

$$\begin{aligned} B_J L G_{hk}^i &= B_J B_h B_k v^i + B_J H_{kh\gamma}^i v^\gamma + H_{kh\gamma}^i B_J v^\gamma \\ &\quad + B_J G_{hk\gamma}^i y^s B_S v^\gamma + G_{hk\gamma}^i y^s B_J B_S v^\gamma \end{aligned}$$

subtracting above two eqn, we get

$$\begin{aligned} B_h L G_{JK}^i - B_J L G_{hk}^i &= \{B_h B_J B_K v^i - B_J B_h B_K v^i\} + v^\gamma (B_h H_{KJ\gamma}^i - B_J H_{kh\gamma}^i) \\ &\quad + H_{KJ\gamma}^i B_h v^\gamma - H_{kh\gamma}^i B_J v^\gamma + (B_h G_{JK\gamma}^i - B_J G_{hk\gamma}^i) y^s B_S v^\gamma \\ &\quad + (G_{JK\gamma}^i B_h B_S v^\gamma - G_{hk\gamma}^i B_J B_S v^\gamma) y^s \\ &= B_K v^\gamma H_{\gamma Jh}^i - B_\gamma v^i H_{kjh}^\gamma - (\cancel{B_\gamma B_K v^i}) H_{jh}^\gamma + v^\gamma (B_h H_{KJ\gamma}^i + B_J H_{kh\gamma}^i) \\ &\quad + H_{KJ\gamma}^i B_h v^\gamma - H_{kh\gamma}^i B_J v^\gamma + (\cancel{H_{\gamma h}^i}) y^s B_S v^\gamma \\ &\quad + (G_{JK\gamma}^i B_h B_S v^\gamma - G_{hk\gamma}^i B_J B_S v^\gamma) y^s \\ &= B_K v^\gamma H_{\gamma Jh}^i - B_\gamma v^i H_{kjh}^\gamma - (\cancel{B_K \cancel{\gamma} v^i} + \cancel{v^s G_{khs}^i}) H_{jh}^\gamma \\ &\quad + v^\gamma (-B_\gamma H_{khj}^i - H_{\gamma h}^s G_{ks}^i - H_{\gamma h}^s G_{ks}^i - \cancel{H_{\gamma h}^s G_{ks\gamma}^i}) + H_{KJ\gamma}^i B_h v^\gamma \\ &\quad - H_{kh\gamma}^i B_J v^\gamma + \cancel{\gamma H_{kjh}^i} \cdot y^s B_S v^\gamma + () y^s \end{aligned}$$

(Using second Bianchi identity)

Since

$$\begin{aligned}\mathcal{L} H_{kjh}^i &= v^r B_r H_{kjh}^i + \partial_r H_{kjh}^i \cdot B_s v^s - H_{kjh}^r B_r v^i + H_{rjh}^i B_r v^r \\ &\quad + H_{krh}^i B_j v^s + H_{rjs}^i B_h v^s\end{aligned}$$

Hence

$$\begin{aligned}B_n \mathcal{L} G_{jk}^i - B_j \mathcal{L} G_{hk}^i &= \mathcal{L} H_{kjh}^i - H_{jrh}^s G_{shk}^i v^r - H_{rnh}^s G_{ksj}^i v^r \\ &\quad + (G_{jrh}^i B_h B_s v^r - G_{hks}^i B_j B_s v^r) v^s \\ &= \mathcal{L} H_{kjh}^i + G_{jrh}^i (B_h B_s v^r \cdot v^s + H_{hs}^r v^s) \\ &\quad + G_{hks}^i (B_j B_s v^r \cdot v^s + H_{js}^r v^s) \\ &= \mathcal{L} H_{kjh}^i + G_{jrh}^i \mathcal{L} G_h^r - G_{hks}^i \mathcal{L} G_j^s\end{aligned}$$

Hence

$$B_n \mathcal{L} G_{jk}^i - B_j \mathcal{L} G_{hk}^i = \mathcal{L} H_{kjh}^i + G_{jrh}^i \mathcal{L} G_h^r - G_{hks}^i \mathcal{L} G_j^s$$

$$\text{Since } \mathcal{L} G_{jk}^i = 0 \Rightarrow \mathcal{L} G_j^i = 0$$

Hence by above identity

$$\mathcal{L} G_{jk}^i = 0 \Rightarrow \mathcal{L} H_{kjh}^i = 0$$

Proved

7. Two processes of Cartan's Covariant differentiation

Let $T_{ij}(x, \dot{x})$ be a second order covariant tensor

field. Then according to second postulate

$$DT_{ij} = dT_{ij} - T_{kj} (\Gamma_{ih}^k dx^h + C_{ih}^k d\dot{x}^h) - T_{ik} (\Gamma_{jh}^k dx^h + C_{jh}^k d\dot{x}^h) \quad \dots \dots \dots (1)$$

Now $Dx^i = dx^i + \lambda^k \Gamma_{kh}^i dx^h + \lambda^k C_{kh}^i d\dot{x}^h$

$$\begin{aligned} D\dot{x}^i &= d\dot{x}^i + \lambda^k \Gamma_{kh}^i dx^h + \frac{\lambda^k}{F} C_{kh}^i d\dot{x}^h \\ &= d\left(\frac{\dot{x}^i}{F}\right) + \lambda^k \Gamma_{kh}^i dx^h \end{aligned}$$

$$= \frac{1}{F} d\dot{x}^i - \frac{dF}{F^2} \dot{x}^i + \lambda^k F_{kh}^i dx^h$$

$$D\dot{x}^i = \frac{1}{F} d\dot{x}^i - \frac{dF}{F} \dot{x}^i + \lambda^k \Gamma_{kh}^i dx^h$$

$$FDx^i = d\dot{x}^i - \lambda^i dF + \dot{x}^k \Gamma_{kh}^i dx^h$$

$$\therefore d\dot{x}^i = FDx^i + \dot{x}^i \frac{dF}{F} - \dot{x}^k \Gamma_{kh}^i dx^h \quad \dots \dots \dots (2)$$

From (1), we have

$$\begin{aligned} DT_{ij} &= \partial_h T_{ij} dx^h + \partial_h T_{ij} d\dot{x}^h - T_{kj} (\Gamma_{ih}^k dx^h + C_{ih}^k d\dot{x}^h) \\ &\quad - T_{ik} (\Gamma_{jh}^k dx^h + C_{jh}^k d\dot{x}^h) \end{aligned}$$

$$\begin{aligned} DT_{ij} &= \partial_h T_{ij} dx^h + \partial_h T_{ij} \left(FDx^h + \frac{\dot{x}^h}{F} dF - \dot{x}^k \Gamma_{kh}^h d\dot{x}^h \right) \\ &\quad - T_{kj} \left\{ \Gamma_{ih}^k dx^h + C_{ih}^k \left(FDx^h + \frac{\dot{x}^h}{F} dF - \dot{x}^k \Gamma_{kh}^h d\dot{x}^h \right) \right\} \\ &\quad - T_{ik} \left\{ \Gamma_{jh}^k dx^h + C_{jh}^k \left(FDx^h + \frac{\dot{x}^h}{F} dF - \dot{x}^k \Gamma_{kh}^h d\dot{x}^h \right) \right\} \end{aligned}$$

$$\text{as } C_{ih}^k \dot{x}^h = 0$$

$$DT_{ij} = \partial_h T_{ij} dx^h + \partial_h T_{ij} (F D)^h + \frac{dF}{F} \dot{x}^h - \dot{x}^k \Gamma_{ph}^h dx^r$$

$$- T_{kj} (\Gamma_{ih}^k dx^h + C_{ih}^k F D^h - C_{ih}^k \Gamma_{pr}^h \dot{x}^p dx^r)$$

$$- T_{ik} (\Gamma_{jh}^k dx^h + C_{jh}^k F D^h - C_{jh}^k \Gamma_{pr}^h \dot{x}^p dx^r)$$

$$DT_{ij} = \{ F \partial_h T_{ij} - F C_{ih}^k T_{kj} - F C_{jh}^k T_{ik} \} D^h$$

$$+ \{ \partial_h T_{ij} - \partial_r T_{ij} \cdot \dot{x}^p \Gamma_{ph}^r - T_{kj} \Gamma_{ih}^k - T_{ik} \Gamma_{jh}^k + C_{ih}^k \Gamma_{ph}^r \dot{x}^p T_{kj} \\ + C_{jh}^k \Gamma_{ph}^r \dot{x}^p T_{ik} \} dx^h + \partial_h T_{ij} \dot{x}^h \frac{dF}{F}$$

$$DT_{ij} = \{ F \partial_h T_{ij} - A_{ih}^k T_{kj} - A_{jh}^k T_{ik} \} D^h$$

$$+ \{ \partial_h T_{ij} - \partial_r T_{ij} \cdot \Gamma_{ph}^{*r} \dot{x}^p - T_{kj} \Gamma_{ih}^{*k} - T_{ik} \Gamma_{jh}^{*k} \} dx^h$$

$$+ \partial_h T_{ij} \dot{x}^h \frac{dF}{F} \quad \text{where } F C_{ih}^k = A_{ih}^k$$

Let us assume that degree of hom. of T_{ij} is zero.

$$\text{then } \partial_h T_{ij} \dot{x}^h = 0$$

$$\text{So } DT_{ij} = T_{ij}|_h D^h + T_{ij}|_h dx^h$$

where $T_{ij}|_h = F \partial_h T_{ij} - A_{ih}^k T_{kj} - A_{jh}^k T_{ik}$ is called Cartan's first covariant derivative of T_{ij} w.r.t. \dot{x}^h .

$T_{ij}|_h = \partial_h T_{ij} - \partial_r T_{ij} \cdot \Gamma_{ph}^{*r} \dot{x}^p - T_{kj} \Gamma_{ih}^{*k} - T_{ik} \Gamma_{jh}^{*k}$ is called Cartan's second covariant derivative of T_{ij} w.r.t. \dot{x}^h .

Γ_{kh}^i is called Cartan's connection coeff.

Schur's Theorem-

If a Finsler space F_n ($n > 2$) is isotropic at each point of a region, and if the scalar $R(x, \dot{x})$ is indep of its directional arguments \dot{x}^i , then the Riemannian curvature is const. throughout that region.

Proof. Bianchi identity for Cartan covariant diff. is

$$K_{\alpha h l s}^i + K_{\alpha h l k}^i + K_{\alpha k l h}^i = \left(\frac{\partial \tilde{F}_k^i}{\partial x^m} K_{\alpha h l}^m + \frac{\partial \tilde{F}_h^i}{\partial x^m} K_{\alpha l k}^m + \frac{\partial \tilde{F}_l^i}{\partial x^m} K_{\alpha k h}^m \right) \dot{x}^s$$

Since $\frac{\partial \tilde{F}_l^i}{\partial x^s} \dot{x}^s = C_{\alpha l s}^h \dot{x}^h$

$$K_{\alpha h l s}^i + K_{\alpha h l k}^i + K_{\alpha k l h}^i + (C_{kmis}^i K_{\alpha h l}^m + C_{hmis}^i K_{\alpha l k}^m + C_{lmis}^i K_{\alpha k h}^m) \dot{x}^s = 0$$

Multiply by \dot{x}^s and noting that $K_{\alpha k h}^i \dot{x}^s = H_{k h}^i$

$$H_{\alpha h l s}^i + H_{\alpha h l k}^i + H_{\alpha k l h}^i + (C_{kmis}^i H_{n l}^m + C_{hmis}^i H_{l k}^m + C_{lmis}^i H_{k h}^m) \dot{x}^s = 0$$

Transvecting by \dot{x}^k , we get

$$H_{\alpha h l s}^i + H_{\alpha h l k}^i \dot{x}^k - H_{\alpha l h}^i + (0 - C_{hmis}^i H_{l}^m + C_{lmis}^i H_{h}^m) \dot{x}^s = 0$$

Now $C_{lmis}^i H_h^m - C_{hmis}^i H_l^m$

$$= C_{lmis}^i \{ F^2 R(s_h^m - l^m)_h \} - C_{hmis}^i \{ F^2 R(s_j^m - l^m)_j \} = 0$$

So above eqⁿ becomes

$$H_{h1J}^i + H_{hJ1K}^i \dot{x}^k - H_{J1h}^i = 0$$

Contracting i & h,

$$(n-1) H_{1J} + H_{J1K}^i \dot{x}^k - H_{11i}^i = 0$$

$$(n-1) H_{1J} + \left(\frac{F^2}{3} \{ (\dot{\gamma}_i R)_{1K} (s_J^i - l_J^i) - (\dot{\gamma}_J R)_{1K} (s_i^i - l_i^i) \} + F R_{1K} (l_i s_J^i - l_J s_i^i) \right)$$

$$- F^2 R_{1i} (s_J^i - l_J^i) = 0$$

$$(n-1) F^2 R_{1J} + \frac{F^2}{3} \{ (\dot{\gamma}_i R)_{1K} (s_J^i - l_J^i) - (\dot{\gamma}_J R)_{1K} (n-1) \} \dot{x}^k + F R_{1K} (1-n) l_J \dot{x}^k$$

$$- F^2 R_{1i} (s_J^i - l_J^i) = 0$$

$$(n-2) F^2 R_{1J} - (n-2) F^2 R_{1K} l_J^k l_J + \frac{F^2}{3} \{ -(n-2) (\dot{\gamma}_J R)_{1K} - (\dot{\gamma}_i R)_{1K} l_J^i l_J \} \dot{x}^k = 0$$

$$(n-2) R_{1J} - (n-2) R_{1K} l_J^k l_J = \frac{1}{3} [(n-2) (\dot{\gamma}_J R)_{1K} + (\dot{\gamma}_i R \cdot \dot{x}^i)_{1K} l_J \cdot \frac{1}{F}] \dot{x}^k$$

$$(n-2) R_{1J} - (n-2) R_{1K} l_J^k l_J = \frac{1}{3} [(n-2) (\dot{\gamma}_J R)_{1K} + 0] \dot{x}^k$$

as degree of hom. of R is zero.

$$R_{1J} - R_{1K} l_J^k l_J = \frac{1}{3} (\dot{\gamma}_J R)_{1K} \cdot \dot{x}^k \quad ; \text{as } n > 2$$

$$3(R_{1J} - R_{1K} l_J^k l_J) = (\dot{\gamma}_J R)_{1K} \dot{x}^k = 0 \quad \text{by assumption } \dot{\gamma}_J R = 0$$

$$R_{1J} = R_{1K} l_J^k l_J \quad \dots \dots (*)$$

diff. w.r.t. \dot{x}^h ,

$$0 = R_{1K} \left\{ \frac{1}{F} (s_h^k - l_h^k) l_J + l^k \cdot \frac{1}{F} (g_{jh} - l_h l_j) \right\}$$

$$0 = R_{1h} l_J + R_{1K} l_J^k g_{jh} - 2 R_{1K} l_J^k l_h l_j$$

$$0 = R_{1K} l_J^k (g_{jh} - l_h l_j) \quad \text{using } (*)$$

so either $g_{lh} - l_h l_j = 0$ or $R_{lk} J^R = 0$

if $g_{lh} = l_h l_j$

$$g_{lh} g^{lm} = l_h l_j g^{lm}$$

$$\delta_h^m = l_h l^m$$

Contracting m & h, we get

$$n = 1 \quad \# \text{ or } n > 2$$

so $R_{lk} J^R = 0$

$$\Rightarrow R_{lk} J^R l_j = 0$$

$$\Rightarrow R_{lj} = 0 \quad \text{using (*)}$$

$$\frac{\partial R}{\partial x^k} \frac{\partial R}{\partial x^j} = 0$$

R is also indep. of position vector. Therefore
R is throughout const.

A

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12/10/14.